

Introduction to Algorithms and Data Structures

11. Graph Algorithms (1) Breadth-first search and Depth-first search

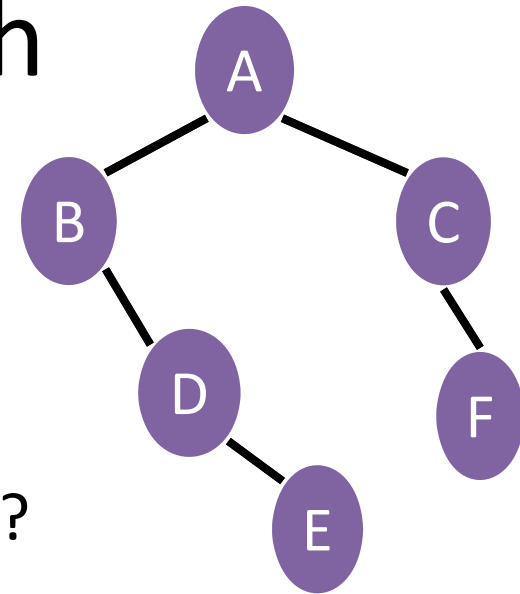
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<http://www.jaist.ac.jp/~uehara/course/2020/myanmar/>

Search in Graph



- How can we check all vertices in a graph **systematically**, and solve some problem?
 - e.g., Do you have a path from A to D?
- Two major (efficient) algorithms:
 - **Breadth First Search**: A -> B -> C -> D -> F -> E
it starts from a vertex v, and visit all (reachable) vertices from the vertices **closer** to v.
 - **Depth First Search**: A -> B -> D -> E -> C -> F
it starts from a vertex v, and visit every reachable vertex from **the current vertex**, and back to the last vertex which has unvisited neighbor.

BFS (Breadth-First Search)

- For a graph $G=(V,E)$ and any start point $s \in V$, all reachable vertices from s will be visited from s in order of distance from s .
- Outline of method: color all vertices by white, gray, or black as follows;
 - White: Unvisited vertex
 - Gray: It is visited, but it has unvisited neighbors
 - Black: It is already visited, and all neighbors are also visited
 - Search is completed when all vertices got black
 - Color of each vertex is changed as white \rightarrow gray \rightarrow black

BFS (Breadth-First Search): Program code

```
BFS(V,E,s){
  for v∈V do toWhite(v); endfor
  toGray(s);
  Q={s};
  while( Q!={} ){
    u=pop(Q); // Q → Q' where Q={u}∪Q'
    for v∈{v∈V|(v,u)∈E}
      if isWhite(v) then
        toGray(v); push(Q,v);
      endif
    endfor
    toBlack(u);
  }
}
```

Queue of gray nodes

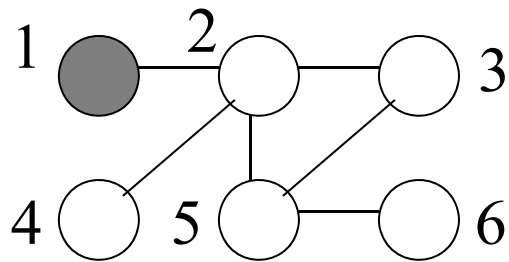
Pop u from left side, which became in gray first

If v, neighbor of u, is white

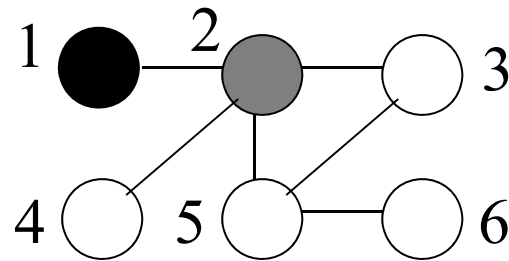
Put v into Q from right, which will be processed last

Make u in black after visiting all neighbors

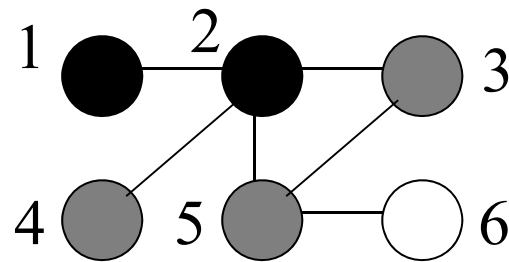
BFS (Breadth-First Search): Example



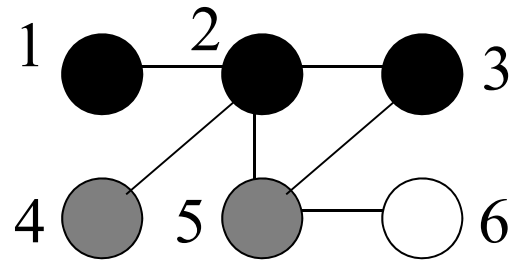
$Q = \{1\}$



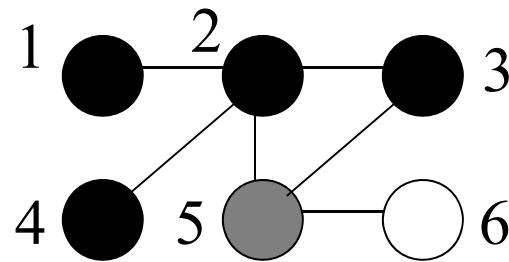
$u = 1,$
visit 2
 $Q = \{2\}$
black 1



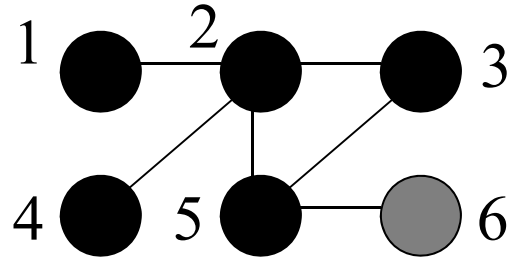
$u = 2,$
visit 3,4,5
 $Q = \{3,4,5\}$
black 2



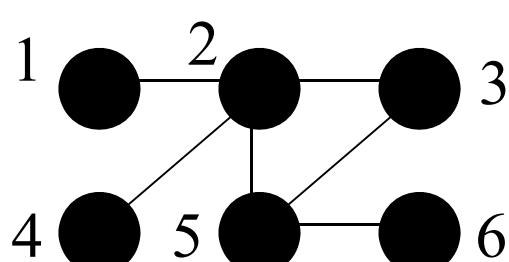
$u = 3,$
visit null
 $Q = \{4,5\}$
black 3



$u = 4,$
visit null
 $Q = \{5\}$
black 4



$u = 5,$
visit 6
 $Q = \{6\}$
black 5



$u = 6,$
visit null
 $Q = \{\}$
black 6

Time complexity is not easy from program...

BFS:

Time complexity

Consider from
the viewpoints of vertices
and edges

- Each vertex never gets white again after initialization.
- Each vertex gets into Q and gets out from Q at most once
- Each edge is checked at most once
 - when one endpoint vertex is taken from Q and its neighbors are checked along edges
- $\therefore O(|V| + |E|)$

Adj. matrix is not good

```
BFS(V,E,s){
  for v∈V do
    toWhite(v);
  endfor
  toGray(s);
  Q={s};
  while( Q!={} ){
    u=pop(Q);
    for v∈{v∈V | (v,u)∈E}
      if isWhite(v) then
        toGray(v);
        push(Q,v);
      endif
    endfor
    toBlack(u);
  }
}
```

Real example code for BFS

```
using System.Collections.Generic;
using static System.Console;

public class i111_12_p7 {
    public static void Main(){
        List<int>[] edges = new List<int>[7];
        edges[1] = new List<int>{2};
        edges[2] = new List<int>{1,3,4,5};
        edges[3] = new List<int>{2,5};
        edges[4] = new List<int>{2};
        edges[5] = new List<int>{2,3,6};
        edges[6] = new List<int>{5};

        bfs(6,edges,1);
    }
}
```

Initialize adj. list for each node

Specify the number of nodes and start node

Initialize by 0 = white

Refer the first node and remove it

Output

```
static void bfs(int n, List<int>[] edges, int s) {
    int[] color = new int[n+1];
    color[s] = 1;
    List<int> q = new List<int>();
    q.Add(s);

    while (q.Count > 0) {
        int u = q[0]; q.RemoveAt(0);
        foreach (int v in edges[u]) {
            if (color[v] == 0) {
                color[v] = 1;
                q.Add(v);
            }
        }
        color[u] = 2;

        Write("u="+u+", Q={ ");
        foreach (int w in q) Write(w+" ");
        Write("}, color={ ");
        for(int i=1; i<=n; i++) Write(color[i]+" ");
        WriteLine("}");
    }
}
```

Queue is realized by List

Application of BFS: Shortest path problem on graph

Definition of “distance”

- Start vertex v has distance 0
- Except start vertex, each vertex u has distance $d+1$, where d is the distance of parent of u .
- On BFS, modify that each gray vertex receives its “distance” from black neighbor, then you get (shortest) distance from v to it.

DFS (Depth-First Search)

- For a graph $G=(V,E)$ and start point $s \in V$, it follows reachable vertices from s **until it reaches a vertex that has no unvisited neighbor**, and returns to the last vertex that has unvisited neighbors.

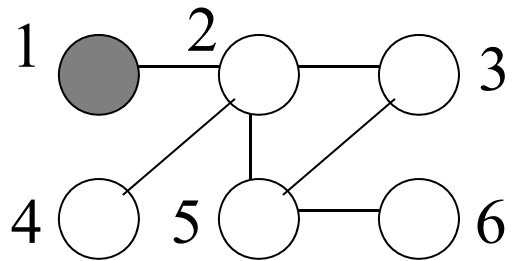
```
dfs(V, E, s) {  
  visit(s) // in gray  
  for (s, w) ∈ E do  
    if notVisited(w) then  
      dfs(V, E, w)  
  toBlack(u)  
}
```

Program code is relatively simple, and vertices are put into a stack when dfs makes a recursive call.

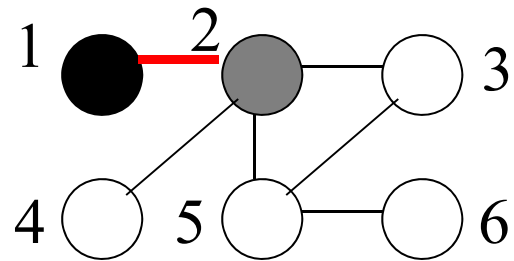
← recursive call of dfs

← make it black after check

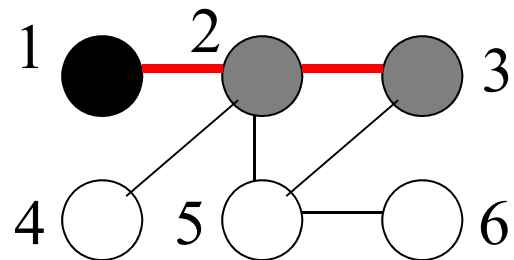
DFS: Example



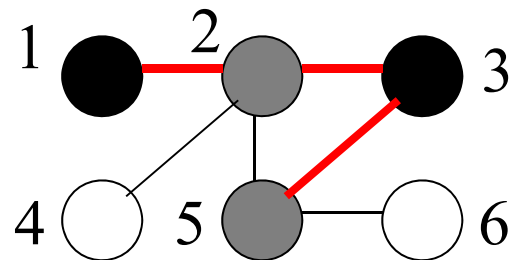
DFS(1)



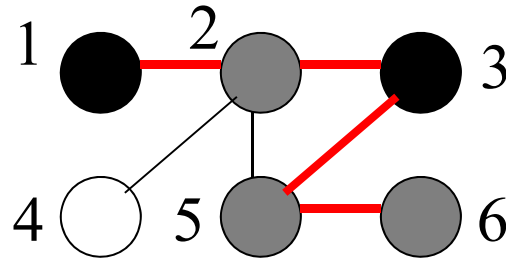
DFS(2)



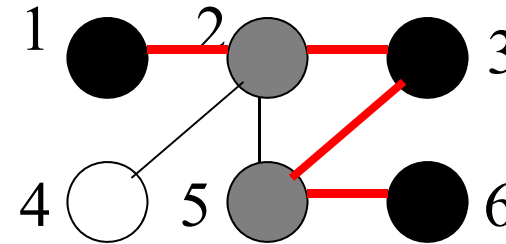
DFS(3)



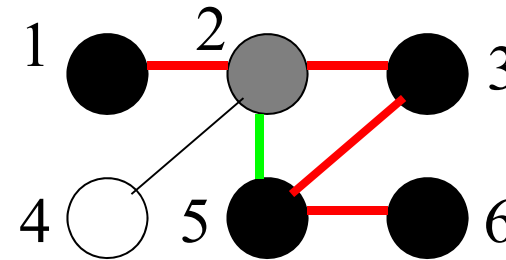
DFS(5)



DFS(6)



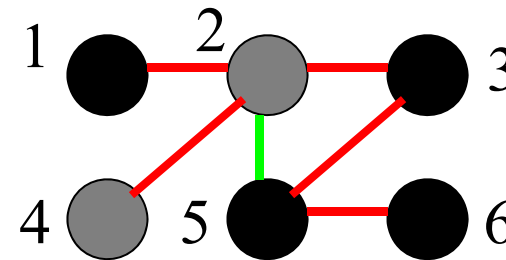
DFS(6)



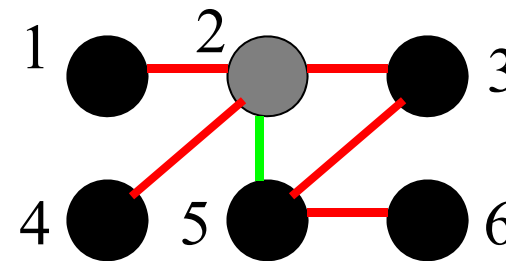
DFS(5)

DFS(3)

DFS(2)



DFS(4)



DFS(2)

Real example code for DFS (by recursive call)

```
using System.Collections.Generic;
using static System.Console;

public class i111_12_p10 {
    public static void Main(){
        List<int>[] edges = new List<int>[7];
        edges[1] = new List<int>{2};
        edges[2] = new List<int>{1,3,4,5};
        edges[3] = new List<int>{2,5};
        edges[4] = new List<int>{2};
        edges[5] = new List<int>{2,3,6};
        edges[6] = new List<int>{5};

        depth = 0;
        color = new int[7];
        WriteLine("dfs(1)");
        dfs(edges,1);
    }
}
```

Initialize adj. list for each node

Body is quite compact!

Specify the start node

```
static int depth;
static int[] color;
```

Colors are kept outside of function
depth is not required (only for output)

```
static void dfs(List<int>[] edges, int u) {
    depth ++;
    color[u] = 1;

    foreach (int v in edges[u]) {
        if (color[v]==0) {
            for (int i=0; i<depth; i++) Write(" ");
            WriteLine("->dfs("+v+"");
            dfs(edges, v);
        }
    }
    depth --;
}
```

Output

Implementation of BFS without recursive call; We can use stack

```
DFS(V,E,s){
  for v∈V do toWhite(v); endfor
  toGray(s);
  S={s};
  while( S!={} ){
    u=pop(S);
    for v∈{v∈V | (u,v)∈E}
      if isnotBlack(v) then
        toGray(v); push(S,v);
      endif
    endfor
    toBlack(u);
  }
}
```

Stack of gray nodes

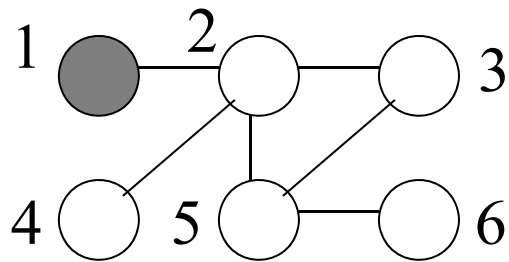
Pop u from the top
which becomes in gray **at last**

If v, neighbor of u, is **not black**,

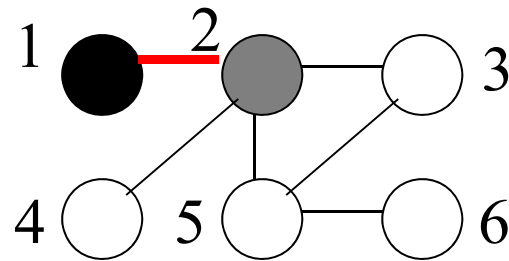
Push v onto S which
will be checked **first**

Make u in black after visiting all neighbors

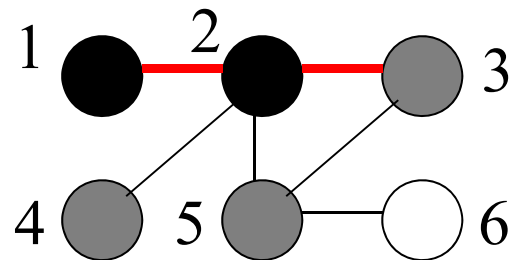
Example of BFS on stack



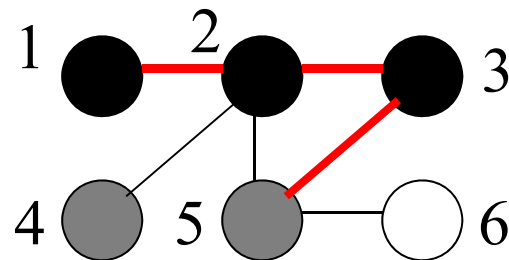
$S = \{1\}$



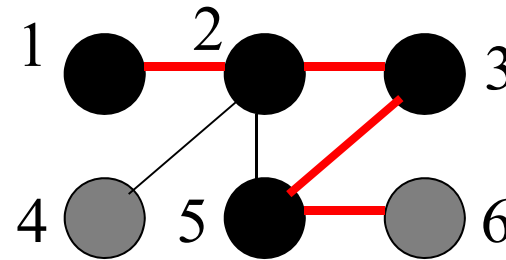
$u=1$
visit 2
 $S = \{2\}$
black 1



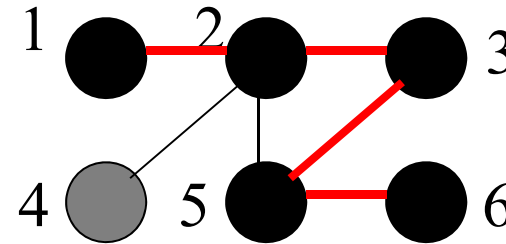
$u=2$
visit 5,4,3
 $S = \{5,4,3\}$
black 2



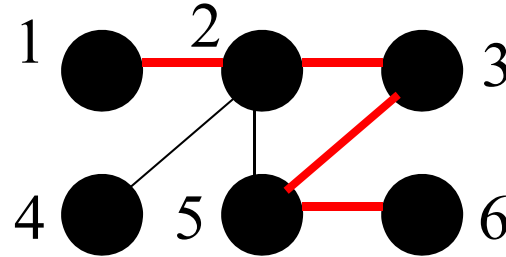
$u=3$
visit 5
 $S = \{5,4,5\}$
black 3



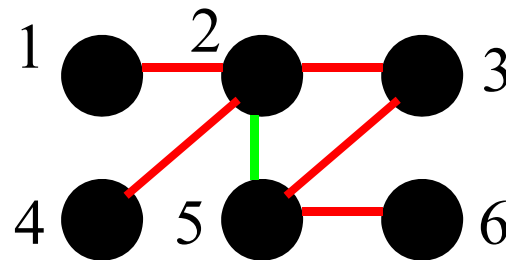
$u=5$
visit 6
 $S = \{5,4,6\}$
black 5



$u=6$
visit null
 $S = \{5,4\}$
black 6



$u=4$
visit null
 $S = \{5\}$
black 4

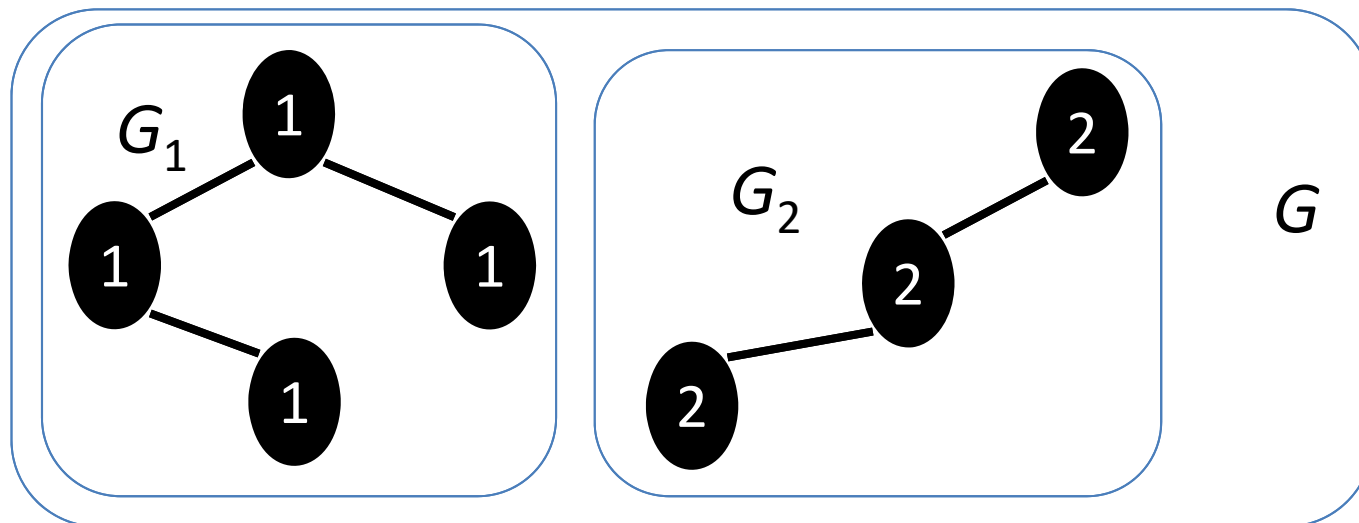


$u=5$
visit null
 $S = \{\}$

Application of DFS:

Find connected components in a graph

- For a given (disconnected) graph $G = (V, E)$, divide it into connected graphs $G_1 = (V_1, E_1), \dots, G_c = (V_c, E_c)$.
 - We will give a numbering array $cn[]$ such that $\forall u, v \in V, u \in V_i \wedge v \in V_j \wedge i \neq j \Rightarrow cn[u] \neq cn[v]$



Application of DFS:

Find connected components of a graph

```
cc(V,E,cn){ //cn[|V|]
  for v∈V do
    cn[v] = 0; /*initialize*/
  endfor
  k = 1;
  for v∈V do
    if cn[v]==0 then
      dfs(V,E,v,k,cn);
      k=k+1;
    endif
  endfor
}
```

```
dfs(V,E,v,k,cn){
  cn[v]=k;
  for u∈{u|(v,u)∈E} do
    if cn[u]==0 then
      dfs(V,E,u,k,cn);
    endif
  endfor
}
```

BFS v.s. DFS on a graph (1)

From the viewpoint of algorithms:

Two major **efficient & simple** search algorithms

– Breadth First Search:

It corresponds to “Queue”

– Depth First Search:

It corresponds to “Stack”

– Both algorithms are easy to implement to run in $O(|V|+|E|)$ time. (In a sense, this time complexity is optimal since you have to check all input data.)

BFS v.s. DFS on a graph (2)

From the practical viewpoint

- BFS
 - Advantage: It can find **shortest path**
 - Disadvantage: It requires memory! (check binary tree of depth n)
- DFS
 - Advantage: It requires **few memory** (proportional to the depth of the graph)
 - Disadvantage: It may find non-shortest path.

Depending on applications, we choose better algorithm.