Introduction to Algorithms and Data Structures

7. Data structure (2) Binary Search Tree and its balancing

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Review:

- We have three combinations of "data structure", "what to do" and "algorithm".
- "What to do": E.g., i-th data, search, add/insert/remove.
- Array: access in O(1), search in O(n)
- Array in order: search in O(log n), but add/remove in O(n)
- Linked list: access in O(n), but add/remove in O(1)
- Hash: easy to add and search
- Binary search tree: <u>dynamic search</u>

Dynamic search and data structure

- Sometimes, we would like to search in dynamic data, i.e., we add/remove data in the data set.
- Example: Document management in university
 - New students: add to list
 - Alumni: remove from list
 - When you get credit: search the list

Q. Good data structure?

Naïve idea: array or linked list?

- Data in order:
 - Search: binary search in O(log n) time
 - Add and remove: O(n) time per data
- Data not in order:
 - Search and remove: O(n) time per data
 - Add: in O(1) time

Imagine: you have 10000 students, and you have 300 new students!

Better idea: binary search tree

- For every vertex v, we have the following;
 - Data in v \geq any data in a vertex in left subtree
 - Data in v \leq any data in a vertex in right subtree



Better idea: binary search tree

- We construct binary search tree for a given data set; we learnt it can be updated in O(L) time, where L is the length of the route from a leaf to the root.
- When data is random:
 - Depth of the tree: O(log n)
 - Search, add, remove: O(log n) time.
- In the worst case:
 - Depth of the tree: n
 - When data is given in order, we have the worst case.
 - Search, add, remove: O(n) time...



Today: More binary search tree (BST)

- 1. Get maximum/minimum data (⇔ heap)
- 2. Enumerate all data in the tree (⇔ array)
- 3. "Good" and "bad" structure?
- 4. How can we fix bad to good?

1. Max/min data in BST

- Properties of a BST
 - All left descendants have smaller values
 - All right descendants have larger values
- Using the properties...
 - Minimum: the leftmost lowest descendant from the root
 - Maximum: the rightmost lowest descendant from the root
- Tips: It is easy to remove the minimum/maximum node (since it has at most one child)



[Review]

How about heap?



- 1. Assign 1 to the root.
- 2. For a node of number i, assign
 2 × i to the left child and assign
 2 × i+1 to the right child.
- 3. No nodes assigned by the number greater than n.
- 4. For each edge, parent stores data smaller than one in child.

We can use <u>an array</u>, instead of linked list!



- It is easy to obtain the minimum one (at root)
- •However, maximum one is not easy in the tree/array

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We have three ways of enumeration (general traverse ways of a binary tree)

• Preorder:

Data in the current node \rightarrow left subtree \rightarrow right subtree

• Inorder:

left subtree \rightarrow Data in the current node \rightarrow right subtree

• Postorder:

left subtree \rightarrow right subtree \rightarrow Data in the current node

× It is easy to enumerate all data in array or linked list

How to traverse binary tree: preorder Data in node \rightarrow left subtree \rightarrow right subtree





How to traverse binary tree: postorder Left subtree \rightarrow right subtree \rightarrow data in node





Small exercise

- Make a small binary search tree (around 10 nodes)
- Find the maximum and minimum data
- Remove the root node
- Enumerate data in preorder, inorder, and postorder



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Efficiency of BST

- Best case: O(log n)
 - Each of n data is kept in BST of depth log₂n
- Worst case: O(n)
 - If we put in increasing order→
 we have depth n
- "Random order" is also interesting topic, but we make it of depth O(log n) in any case.





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Nice idea: (Self-)Balanced Binary Search Tree

- There are some algorithms that maintain to take balance of tree in depth $O(\log n)$.
 - e.g., AVL tree, 2-3 tree, 2-color tree (red-black tree)



Georgy M. Adelson-Velsky (1922–2014)



Evgenii M. Landis (1921–1997)

AVL tree [G.M. Adelson-Velskii and E.M. Landis '62]

- Property (or assertion): at each vertex, the depth of left subtree and right subtree differs at most 1.
- Example:

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AVL tree: Insertion of data

- Find a leaf v for a new data x We have nothing to do up to here
- Store data x into v (v is not a leaf any more)
- Check the change of balance by insertion of x
- From v to the root, check the balance at each vertex, and rebalance (rotation) if necessary.



What happens if you insert x=4? How about x=10, x=20, x=23?



Balance: OK





Balance: OK



0;2@vertex221

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AVL tree: Rebalance by rotations

- If you insert/remove data, the BST can get unbalanced.
- "Rotate" tree vertices to make the difference up to 1:
 - Rotation LL
 - Rotation RR
 - Double rotation LR
 - Double rotation RL

Rebalance of AVL-tree by rotation: Rotation LL

 Lift up left subtree (yellow) if too deep we have to transplant right subtree (blue)

Right child of q Now we have balanced not break balance Left child of p condition of BST



Rebalance of AVL-tree by rotation: Rotation RR (just mirror image of LL)

Child of p

• Lift up right subtree (green) if too deep we have to transplant left subtree (blue)

Child of

AVL tree: Rebalance by rotation: Double rotation LR

• When right subtree of left subtree becomes too deep, lift up the left-right subtree.

* Condition is satisfied?* Why rotation LL does not work?

AVL tree: Rebalance by rotation: Double rotation LR

• When right subtree of left subtree becomes too deep, lift up the left-right subtree.



※Condition is satisfied?※Why rotation LL does not work?

(If you apply rotation LL)



AVL tree: Rebalance by rotation: Double rotation RL (just mirror image of LR)

• When left subtree of right subtree becomes too deep, lift up the right-left subtree.

Insertion of 8



• Insertion of 6



• Insertion of 4 (balance is okay)



• Deletion of 6



• Insertion of 6 (balance is okay)



• Deletion of 8



Time complexity of balanced binary search tree

- Search: $O(\log n)$ time
- Insertion/Deletion: O(log n) time
 - $-O(\log n)$ rotations
 - Each rotation takes constant time
- In total, on a balanced binary search tree, every operation can be done in O(log n) time.
 (n is the number of data in the tree)