

Introduction to Algorithms and Data Structures

Lecture 14: Graph Algorithms (1) Breadth-first search and Depth-first search

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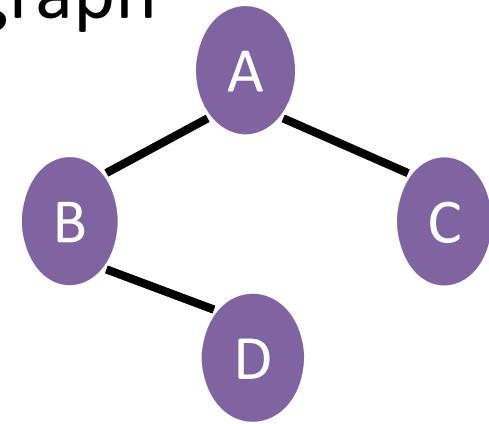
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Search in Graph

- How can we check all vertices in a graph **systematically**, and solve some problem?

- e.g., Do you have a path from A to D?



- Two major (efficient) algorithms:
 - **Breadth First Search**: A -> B -> C -> D
it starts from a vertex v, and visit all (reachable) vertices from the vertices **closer** to v.
 - **Depth First Search**: A -> B -> D -> C
it starts from a vertex v, and visit every reachable vertex from **the current vertex**, and back to the last vertex which has unvisited neighbor.

BFS (Breadth-First Search)

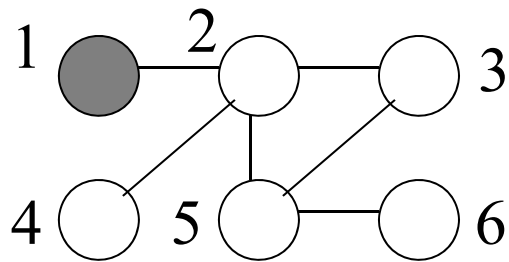
- For a graph $G=(V,E)$ and any start point $s \in V$, all reachable vertices from s will be visited from s in order of distance from s .
- Outline of method: color all vertices by white, gray, or black as follows;
 - White: Unvisited vertex
 - Gray: It is visited, but it has unvisited neighbors
 - Black: It is already visited, and all neighbors are also visited
 - Search is completed when all vertices got black
 - Color of each vertex is changed as white \rightarrow gray \rightarrow black

BFS (Breadth-First Search): Program code

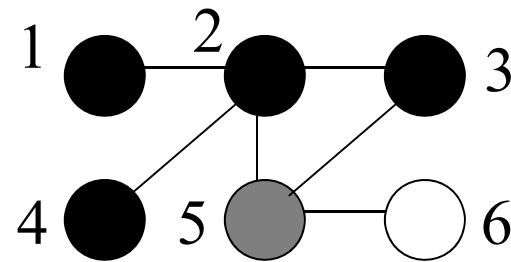
```
BFS(V,E,s){
  for v∈V do toWhite(v); endfor
  toGray(s);
  Q={s};
  while( Q!={} ){
    u=pop(Q); // Q → Q' where Q={u}∪Q'
    for v∈{v∈V|(v,u)∈E}
      if isWhite(v) then
        toGray(v); push(Q,v);
      endif
    endfor
    toBlack(u);
  }
}
```

Queue is the best data structure for this purpose!

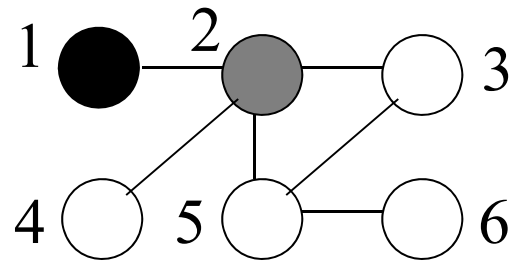
BFS (Breadth-First Search): Example



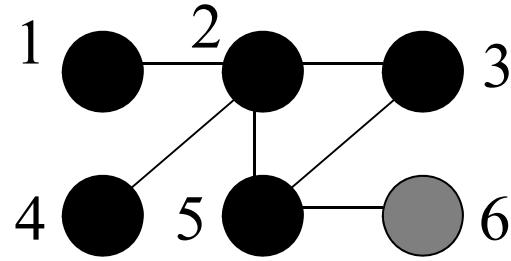
$Q = \{1\}$



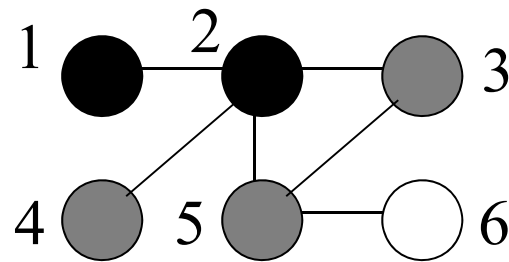
$u = 4,$
visit null
 $Q = \{5\}$
black 4



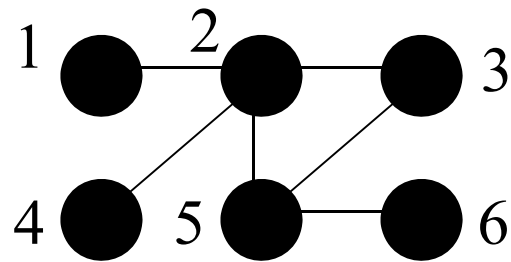
$u = 1,$
visit 2
 $Q = \{2\}$
black 1



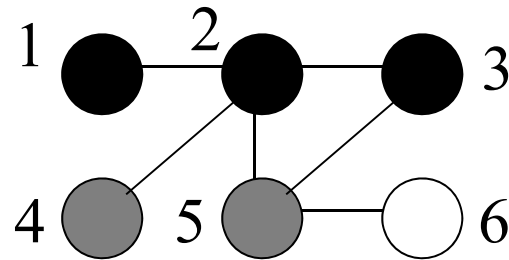
$u = 5,$
visit 6
 $Q = \{6\}$
black 5



$u = 2,$
visit 3,4,5
 $Q = \{3,4,5\}$
black 2



$u = 6,$
visit null
 $Q = \{\}$
black 6



$u = 3,$
visit null
 $Q = \{4,5\}$
black 3

Time complexity is not easy from program...

BFS:

Time complexity

Consider from
the viewpoints of vertices
and edges

- Each vertex never gets white again after initialization.
- Each vertex gets into Q and gets out from Q at most once
- Each edge is checked at most once
 - when one endpoint vertex is taken from Q and its neighbors are checked along edges
- $\therefore O(|V| + |E|)$

```
BFS(V, E, s) {
  for v ∈ V do
    toWhite(v);
  endfor
  toGray(s);
  Q = {s};
  while( Q ≠ {} ) {
    u = pop(Q);
    for v ∈ {v ∈ V | (v, u) ∈ E}
      if isWhite(v) then
        toGray(v);
        push(Q, v);
      endif
    endfor
    toBlack(u);
  }
}
```

Application of BFS: Shortest path problem on graph

Definition of “distance”

- Start vertex v has distance 0
- Except start vertex, each vertex u has distance $d+1$, where d is the distance of parent of u .
- On BFS, modify that each gray vertex receives its “distance” from black neighbor, then you get (shortest) distance from v to it.

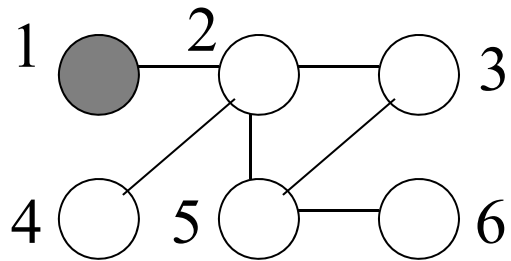
DFS (Depth-First Search)

- For a graph $G=(V,E)$ and start point $s \in V$, it follows reachable vertices from s until it reaches a vertex that has no unvisited neighbor, and returns to the last vertex that has unvisited neighbors.

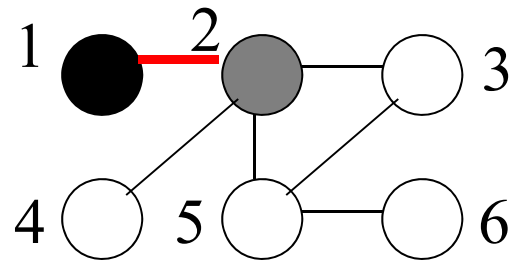
```
dfs(V, E, s) {  
    visit(s)  
    for (s, w) ∈ E do  
        if notVisited(w) then  
            dfs(V, E, w)  
}
```

Program code is relatively simple, and vertices are put into a stack when dfs makes a recursive call.

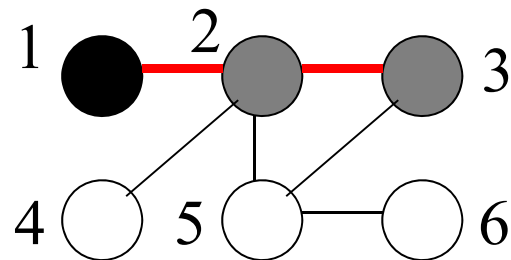
DFS: Example



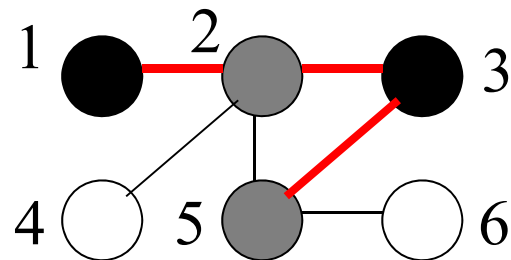
DFS(1)



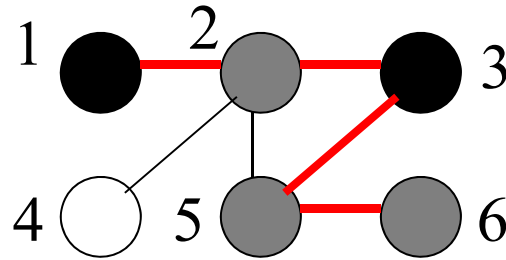
DFS(2)



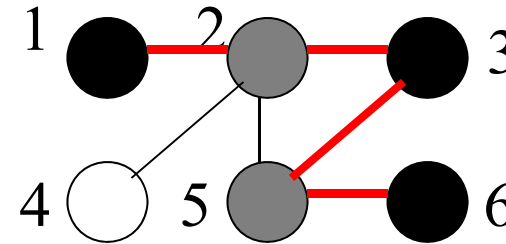
DFS(3)



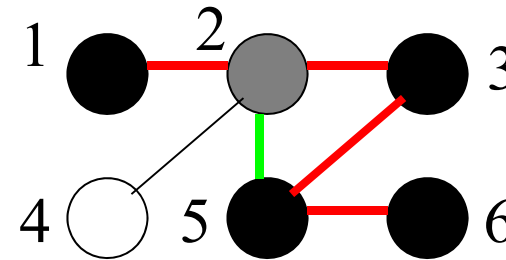
DFS(5)



DFS(6)



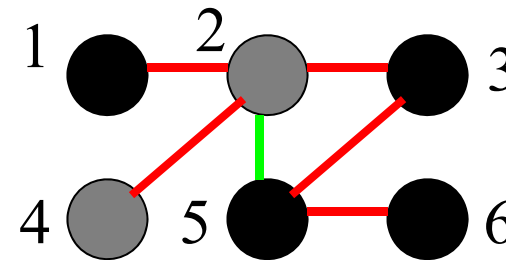
DFS(6)



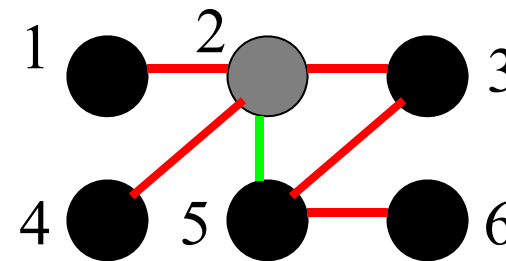
DFS(5)

DFS(3)

DFS(2)



DFS(4)

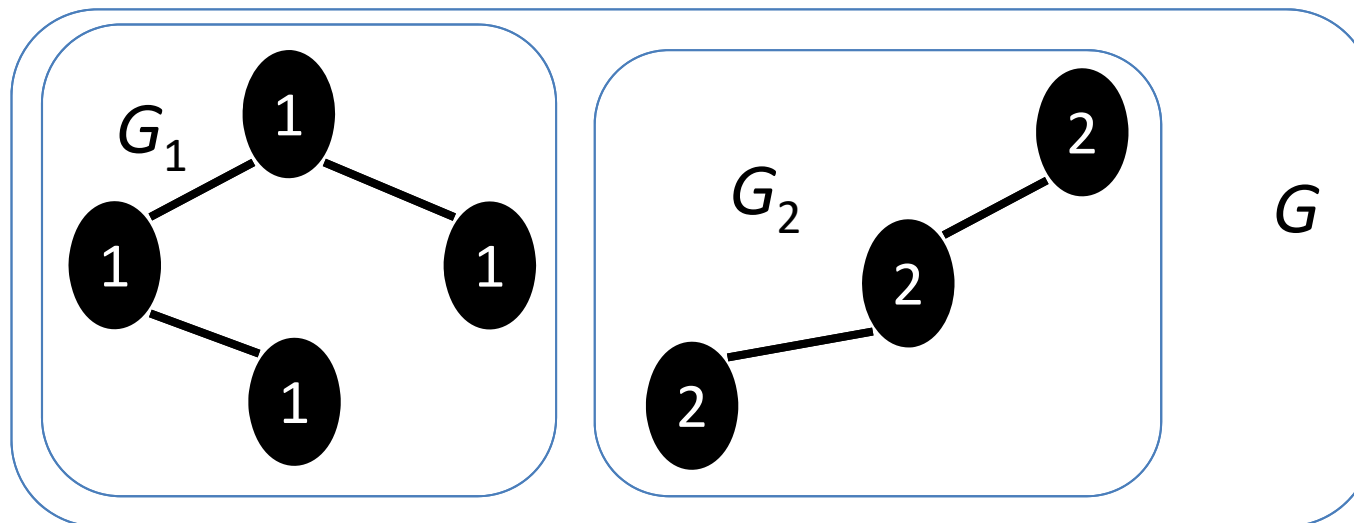


DFS(2)

Application of DFS:

Find connected components in a graph

- For a given (disconnected) graph $G = (V, E)$, divide it into connected graphs $G_1 = (V_1, E_1), \dots, G_c = (V_c, E_c)$.
 - We will give a numbering array $cn[]$ such that
 $u, v \in V, u \in V_i, v \in V_j, i \neq j \implies cn[u] \neq cn[v]$



Application of DFS:

Find connected components of a graph

```
cc(V,E,cn){ //cn[|V|]
  for v∈V do
    cn[v] = 0; /*initialize*/
  endfor
  k = 1;
  for v∈V do
    if cn[v]==0 then
      dfs(V,E,v,k,cn);
      k=k+1;
    endif
  endfor
}
```

```
dfs(V,E,v,k,cn){
  cn[v]=k;
  for u∈{u|(v,u)∈E} do
    if cn[u]==0 then
      dfs(V,E,u,k,cn);
    endif
  endfor
}
```

BFS v.s. DFS on a graph

- Two major (efficient) algorithms:
 - Breadth First Search:
 - It corresponds to “Queue”
 - Depth First Search:
 - It corresponds to “Stack”
 - Both algorithms are easy to implement to run in $O(|V|+|E|)$ time. (In a sense, this time complexity is optimal since you have to check all input data.)
 - Depending on applications, we choose better algorithm.