

実践的アルゴリズム理論 Theory of Advanced Algorithms

グラフのデータ構造

担当: 上原隆平

Theory of Advanced Algorithms

実践的アルゴリズム理論

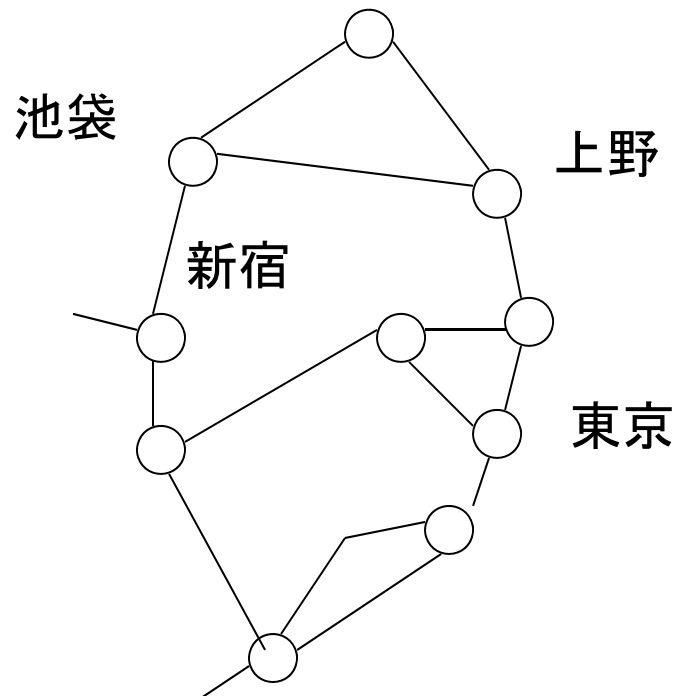
Data Structure of Graphs

Ryuhei Uehara

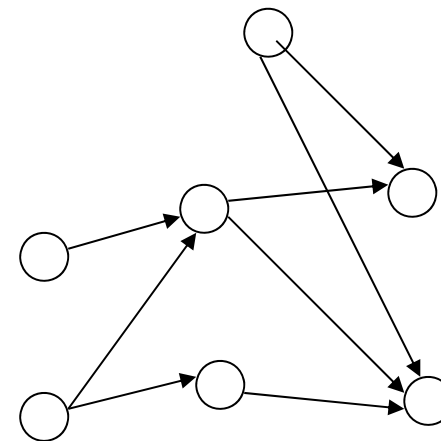
グラフ (graph)

- 頂点を辺で結んだもの
 - 有向グラフ: 辺に方向がある
 - 無向グラフ: 辺に方向がない

例: 路線図



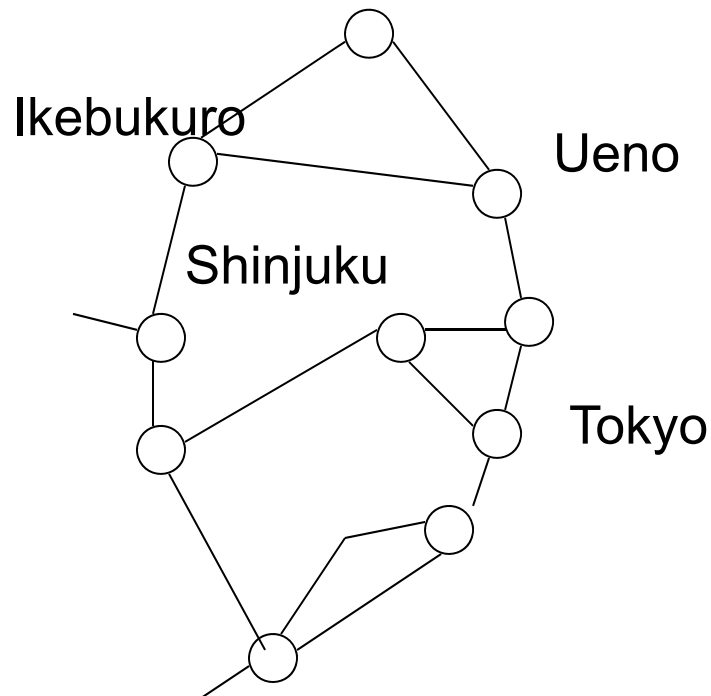
例: 講義の履修順序



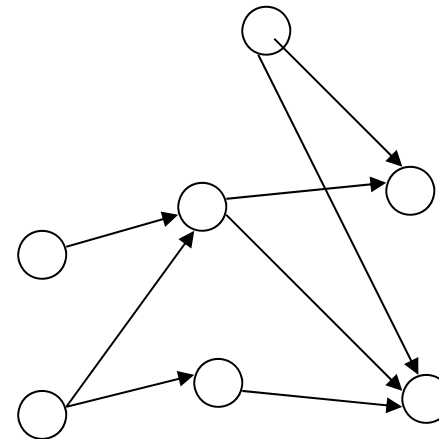
Graph

- Vertices are joined by edges
 - Directed graph: each edge has direction
 - (Undirected) graph: each edge has no direction

Example: Railmap

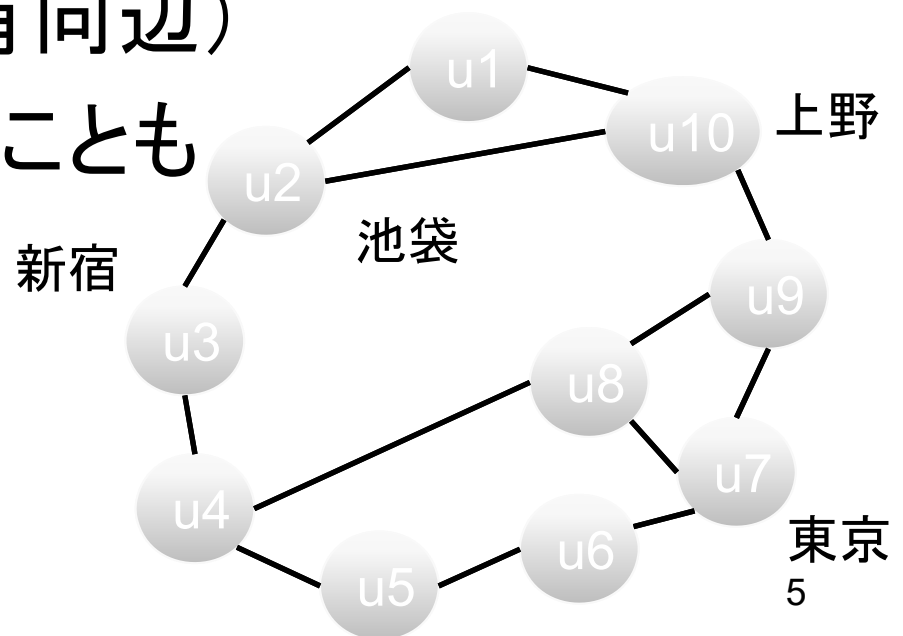


Example: Order of classes



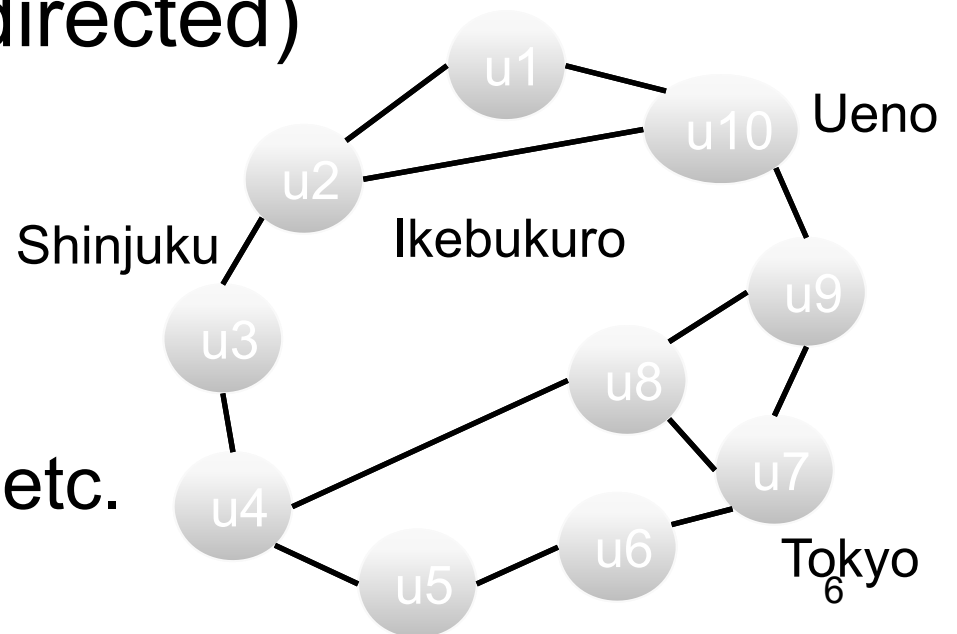
グラフ: 表記

- グラフ: $G = (V, E)$
 - V : 頂点集合, E : 辺集合
- 頂点: $u, v, \dots \in V$
- 辺: $e = \{u, v\} \in E$ (無向辺)
 $a = (u, v) \in E$ (有向辺)
- 頂点や辺は重みを持つことも
 - $w(u), w(e)$
 - 距離, 金額, 時間など



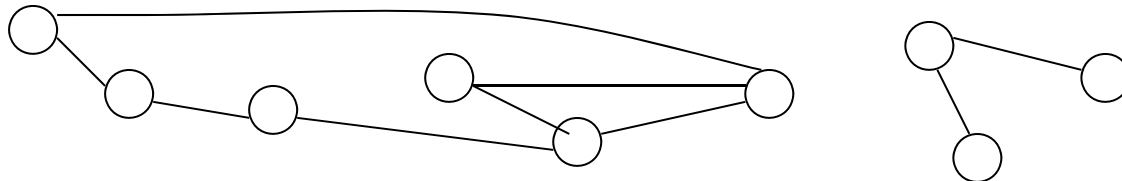
Graph: Notation

- Graph: $G = (V, E)$
 - V : Vertex set, E : Edge set
- Vertices: $u, v, \dots \in V$
- Edges: $e = \{u, v\} \in E$ (undirected)
 $a = (u, v) \in E$ (directed)
- Vertices/edges can have weight
 - $w(u)$, $w(e)$
 - Distance, price, time, etc.

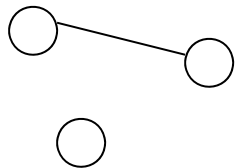


グラフ: 基本的な用語 (1/2)

- 路 (path): 辺で隣り合う頂点を繋いだもの
 - 単純路 (simple path): 同じ頂点を複数回通らない

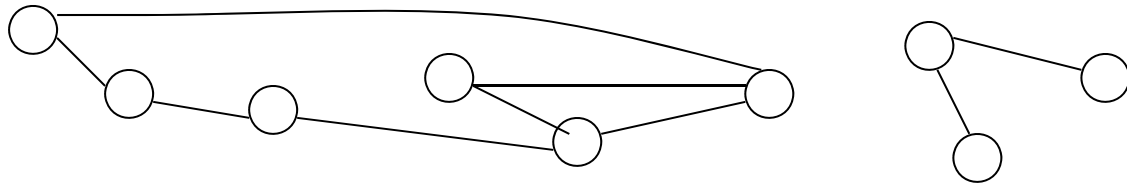


- 閉路 (cycle, closed path): v から v への路
- 連結グラフ (connected graph): どの2頂点間にも路が存在するグラフ

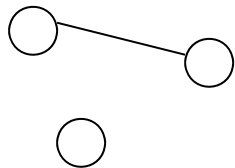


Graph: Basic terms (1/2)

- Path: Vertices joined by edges
 - Simple path: never visits the same vertex twice

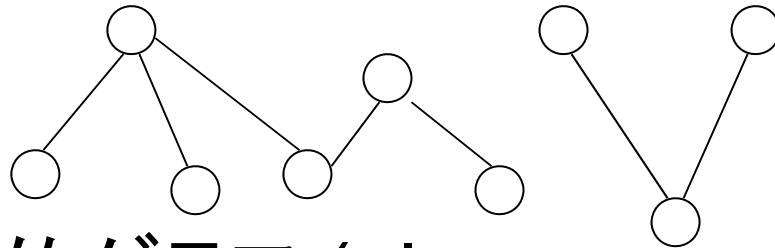


- cycle, closed path: path from v to v
- connected graph: Any pair of vertices is joined by a path

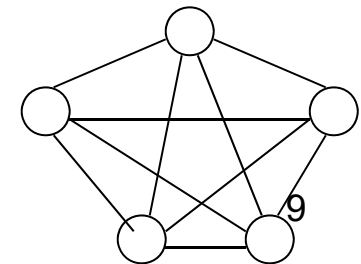


グラフ: 基本的な用語 (2/2)

- 森 (forest): 閉路を含まないグラフ
- 木 (tree): 連結で閉路を含まないグラフ

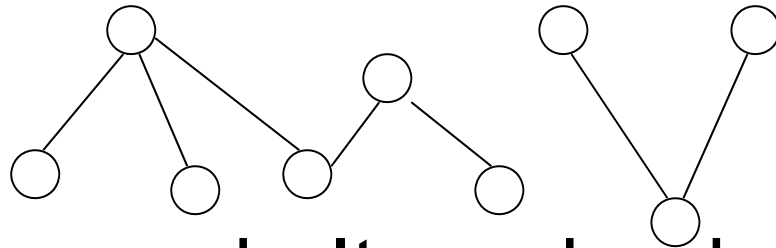


- 平面的グラフ (planar graph): 辺の交差なしで平面に描画できるグラフ
- 完全グラフ (complete graph): 全ての頂点对を辺で隣接させたグラフ
 - 完全グラフ K_5 は極小非平面的グラフ

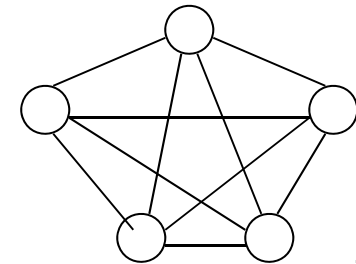


Graph: Basic terms (2/2)

- forest: acyclic graph (no cycle)
- tree: connected acyclic graph



- planar graph: It can be drawn on a plane without crossing of edges
- complete graph: graph s. t. all pairs are joined
 - Complete graph K_5 is a minimal non-planar graph



グラフアルゴリズムの計算量

- 頂点数 n , 辺数 $m \in O(n^2)$
 - 無向グラフ: $m \leq n(n-1)/2$
 - 有向グラフ: $m \leq n(n-1)$
- 平面グラフでは $m \in O(n)$
- グラフアルゴリズムの計算量は n や m の式で表す

Complexity of graph algorithms

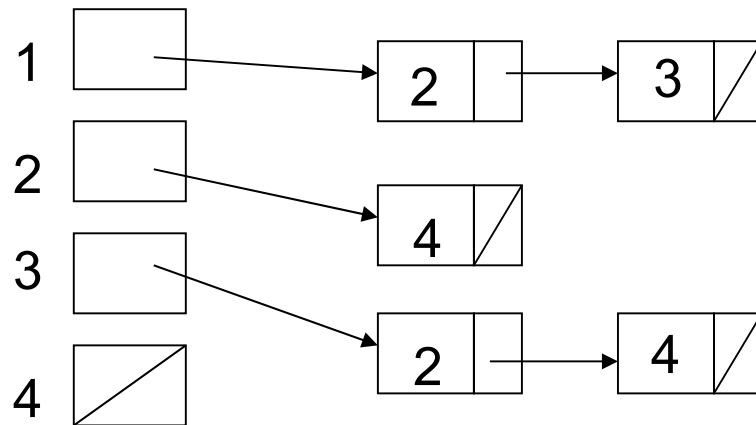
- n vertices and m edges; $m \in O(n^2)$
 - undirected graph: $m \leq n(n-1)/2$
 - directed graph: $m \leq n(n-1)$
- On a plane graph, $m \in O(n)$
- Computational complexity of a graph algorithm is given by an expression of n, m

グラフの表現方法

- 隣接行列

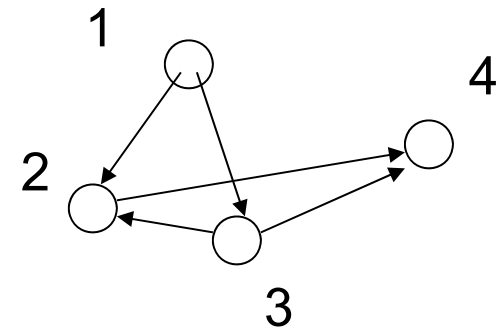
$$M = \begin{pmatrix} 0 & 1 & 1 & 0 \\ 0 & 0 & 0 & 1 \\ 0 & 1 & 0 & 1 \\ 0 & 0 & 0 & 0 \end{pmatrix}$$

- 隣接リスト



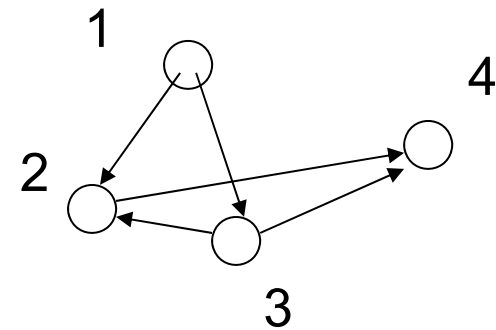
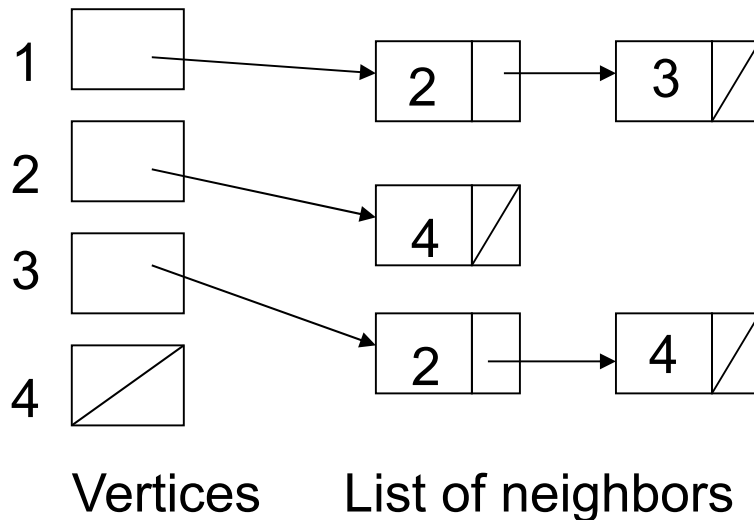
頂点

隣接頂点のリスト



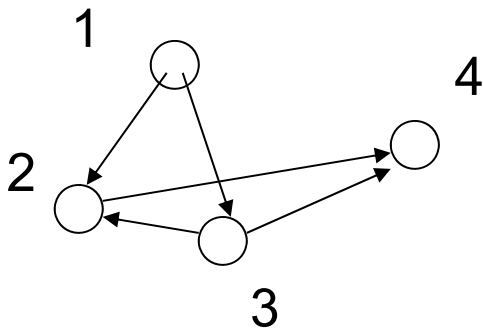
Representation of a graph

- Adjacency matrix
$$M = \begin{pmatrix} 0 & 1 & 1 & 0 \\ 0 & 0 & 0 & 1 \\ 0 & 1 & 0 & 1 \\ 0 & 0 & 0 & 0 \end{pmatrix}$$
- Adjacency list



グラフの表現方法: 行列表現(隣接行列)

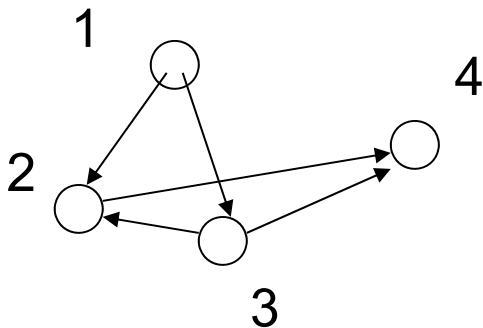
- $(u, v) \in E \Rightarrow M[u, v] = 1$
- $(u, v) \notin E \Rightarrow M[u, v] = 0$



$$M = \begin{pmatrix} 0 & 1 & 1 & 0 \\ 0 & 0 & 0 & 1 \\ 0 & 1 & 0 & 1 \\ 0 & 0 & 0 & 0 \end{pmatrix}$$

Representation of a graph: Matrix representation (adj. matrix)

- $(u, v) \in E \Rightarrow M[u, v] = 1$
- $(u, v) \notin E \Rightarrow M[u, v] = 0$

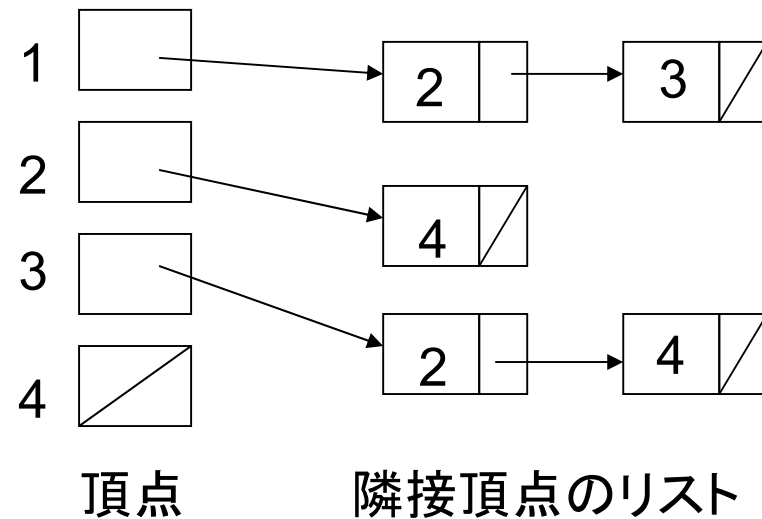
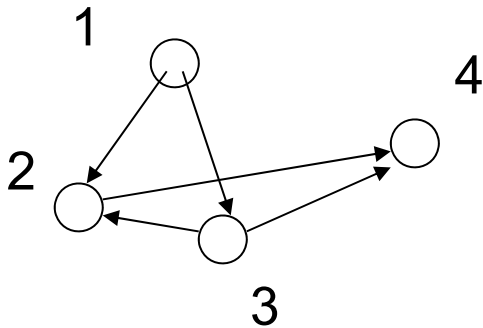


$$M = \begin{pmatrix} 0 & 1 & 1 & 0 \\ 0 & 0 & 0 & 1 \\ 0 & 1 & 0 & 1 \\ 0 & 0 & 0 & 0 \end{pmatrix}$$

グラフの表現方法: リスト表現(隣接リスト)

- $(u, v) \in E \Leftrightarrow v \in T(u)$
 - $T(u)$ は u の隣接点のリスト

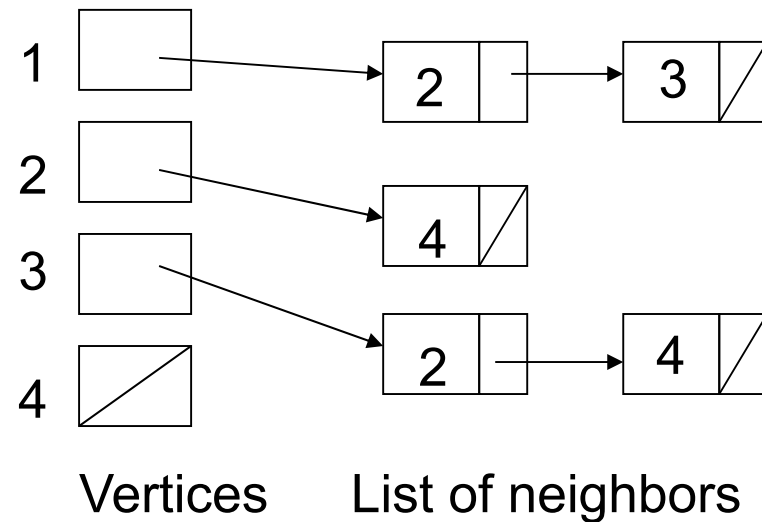
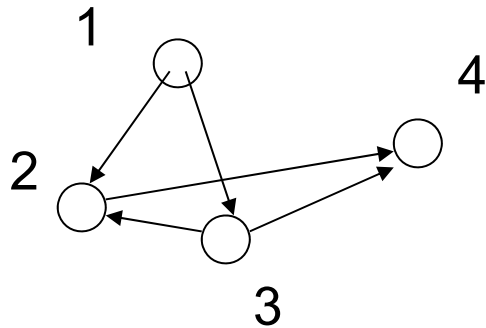
- 例:



Representation of a graph: List representation (adj. list)

- $(u, v) \in E \Leftrightarrow v \in T(u)$
 - $T(u)$ is the list of neighbors of u

- Example:



隣接行列 vs 隣接リスト

- メモリ量
 - 隣接行列: $\Theta(n^2)$
 - 隣接リスト: $\Theta(m \log n)$
- 隣接チェックにかかる時間: $(u, v) \in E$?
 - 隣接行列: $\Theta(1)$
 - 隣接リスト: $\Theta(n)$

Q. グラフの更新 (e.g., 頂点・辺の追加・削除) は？

Adj. Matrix vs Adj. List

- Memory
 - Adj. matrix: $\Theta(n^2)$
 - Adj. list: $\Theta(m \log n)$
- Time for check if $(u, v) \in E$?
 - Adj. matrix: $\Theta(1)$
 - Adj. list: $\Theta(n)$

Q. Update of graph?
(e.g., add/remove of vertex/edge)